AP Summer 2019.

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AP® Physics 1: Algebra-Based
2019 Free-Response Questions

CollegeBoard

AP® PHYSICS 1 TABLE OF INFORMATION

CONSTANTS AND CONVERSION FACTORS	
Proton mass, $m_p = 1.67 \times 10^{-27}$ kg	Electron charge magnitude, $e = 1.60 \times 10^{-19}$ C
Neutron mass, $m_n = 1.67 \times 10^{-27}$ kg	Coulomb's law constant, $k = 1/4\pi\varepsilon_0 = 9.0 \times 10^9\ \text{N}\cdot\text{m}^2/\text{C}^2$
Electron mass, $m_e = 9.11 \times 10^{-31}$ kg	Universal gravitational constant, $G = 6.67 \times 10^{-11}\ \text{m}^3/\text{kg}\cdot\text{s}^2$
Speed of light, $c = 3.00 \times 10^8$ m/s	Acceleration due to gravity at Earth's surface, $g = 9.8\ \text{m/s}^2$

UNIT SYMBOLS								
	meter,	m	kelvin,	K	watt,	W	degree Celsius,	°C
	kilogram,	kg	hertz,	Hz	coulomb,	C		
	second,	s	newton,	N	volt,	V		
	ampere,	A	joule,	J	ohm,	Ω		

PREFIXES		
Factor	Prefix	Symbol
10^{12}	tera	T
10^{9}	giga	G
10^{6}	mega	M
10^{3}	kilo	k
10^{-2}	centi	c
10^{-3}	milli	m
10^{-6}	micro	μ
10^{-9}	nano	n
10^{-12}	pico	p

VALUES OF TRIGONOMETRIC FUNCTIONS FOR COMMON ANGLES							
θ	0°	30°	37°	45°	53°	60°	90°
$\sin\theta$	0	1/2	3/5	$\sqrt{2}/2$	4/5	$\sqrt{3}/2$	1
$\cos\theta$	1	$\sqrt{3}/2$	4/5	$\sqrt{2}/2$	3/5	1/2	0
$\tan\theta$	0	$\sqrt{3}/3$	3/4	1	4/3	$\sqrt{3}$	∞

The following conventions are used in this exam.

I. The frame of reference of any problem is assumed to be inertial unless otherwise stated.
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AP® PHYSICS 1 EQUATIONS

MECHANICS

$v_x = v_{x0} + a_x t$

$x = x_0 + v_{x0}t + \frac{1}{2}a_x t^2$

$v_x^2 = v_{x0}^2 + 2a_x(x - x_0)$

$\vec{a} = \frac{\sum \vec{F}}{m} = \frac{\vec{F}_{net}}{m}$

$|\vec{F}_f| \leq \mu |\vec{F}_n|$

$a_c = \frac{v^2}{r}$

$\vec{p} = m\vec{v}$

$\Delta\vec{p} = \vec{F}\Delta t$

$K = \frac{1}{2}mv^2$

$\Delta E = W = F_{\parallel}d = Fd\cos\theta$

$P = \frac{\Delta E}{\Delta t}$

$\theta = \theta_0 + \omega_0 t + \frac{1}{2}\alpha t^2$

$\omega = \omega_0 + \alpha t$

$x = A\cos(2\pi f t)$

$\vec{\alpha} = \frac{\sum \vec{\tau}}{I} = \frac{\vec{\tau}_{net}}{I}$

$\tau = r_{\perp}F = rF\sin\theta$

$L = I\omega$

$\Delta L = \tau \Delta t$

$K = \frac{1}{2}I\omega^2$

$|\vec{F}_s| = k|\vec{x}|$

$U_s = \frac{1}{2}kx^2$

$\rho = \frac{m}{V}$

a = acceleration
A = amplitude
d = distance
E = energy
f = frequency
F = force
I = rotational inertia
K = kinetic energy
k = spring constant
L = angular momentum
ℓ = length
m = mass
P = power
p = momentum
r = radius or separation
T = period
t = time
U = potential energy
V = volume
v = speed
W = work done on a system
x = position
y = height
α = angular acceleration
μ = coefficient of friction
θ = angle
ρ = density
τ = torque
ω = angular speed

$\Delta U_g = mg\Delta y$

$T = \frac{2\pi}{\omega} = \frac{1}{f}$

$T_s = 2\pi\sqrt{\frac{m}{k}}$

$T_p = 2\pi\sqrt{\frac{\ell}{g}}$

$|\vec{F}_g| = G\frac{m_1 m_2}{r^2}$

$\vec{g} = \frac{\vec{F}_g}{m}$

$U_G = -\frac{Gm_1 m_2}{r}$

ELECTRICITY

$|\vec{F}_E| = k\left|\frac{q_1 q_2}{r^2}\right|$

$I = \frac{\Delta q}{\Delta t}$

$R = \frac{\rho \ell}{A}$

$I = \frac{\Delta V}{R}$

$P = I\Delta V$

$R_s = \sum_i R_i$

$\frac{1}{R_p} = \sum_i \frac{1}{R_i}$

A = area
F = force
I = current
ℓ = length
P = power
q = charge
R = resistance
r = separation
t = time
V = electric potential
ρ = resistivity

WAVES

$\lambda = \frac{v}{f}$

f = frequency
v = speed
λ = wavelength

GEOMETRY AND TRIGONOMETRY

Rectangle
$A = bh$

Triangle
$A = \frac{1}{2}bh$

Circle
$A = \pi r^2$
$C = 2\pi r$

Rectangular solid
$V = \ell wh$

Cylinder
$V = \pi r^2 \ell$
$S = 2\pi r\ell + 2\pi r^2$

Sphere
$V = \frac{4}{3}\pi r^3$
$S = 4\pi r^2$

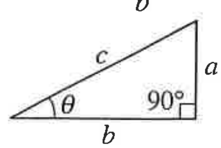
A = area
C = circumference
V = volume
S = surface area
b = base
h = height
ℓ = length
w = width
r = radius

Right triangle
$c^2 = a^2 + b^2$

$\sin\theta = \frac{a}{c}$

$\cos\theta = \frac{b}{c}$

$\tan\theta = \frac{a}{b}$



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2. (12 points, suggested time 25 minutes)

   Some students want to know what gets used up in an incandescent lightbulb when it is in series with a resistor: current, energy, or both. They come up with the following two questions.

   (1) In one second, do fewer electrons leave the bulb than enter the bulb?
   (2) Does the electric potential energy of electrons change while inside the bulb?

   The students have an adjustable power source, insulated wire, lightbulbs, resistors, switches, voltmeters, ammeters, and other standard lab equipment. Assume that the power supply and voltmeters are marked in 0.1 V increments and the ammeters are marked in 0.01 A increments.

   (a) Describe an experimental procedure that could be used to answer questions (1) and (2) above. In your description, state the measurements you would make and how you would use the equipment to make them. Include a neat, labeled diagram of your setup.

   (b)
      i. Explain how data from the experiment you described can be used to answer question (1) above.
      ii. Explain how data from the experiment you described can be used to answer question (2) above.

   A lightbulb is nonohmic if its resistance changes as a function of current. Your setup from part (a) is to be used or modified to determine whether the lightbulb is nonohmic.

   (c)
      i. How, if at all, does the setup need to be modified?
      ii. What additional data, if any, would need to be collected?

   (d) How would you analyze the data to determine whether the bulb is nonohmic? Include a discussion of how the uncertainties in the voltmeters and ammeters would affect your argument for concluding whether the resistor is nonohmic.

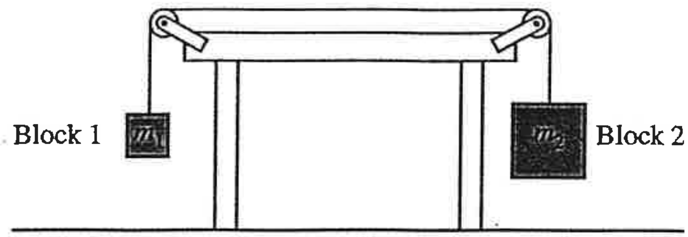
PHYSICS 1

Section II

5 Questions

Time—90 minutes

Directions: Questions 1, 4 and 5 are short free-response questions that require about 13 minutes each to answer and are worth 7 points each. Questions 2 and 3 are long free-response questions that require about 25 minutes each to answer and are worth 12 points each. Show your work for each part in the space provided after that part.



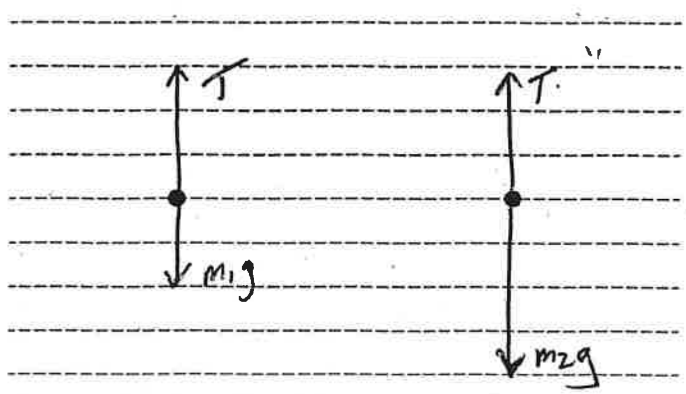
Note: Figure not drawn to scale.

1. (7 points, suggested time 13 minutes)

   Two blocks are connected by a string of negligible mass that passes over massless pulleys that turn with negligible friction, as shown in the figure above. The mass m_2 of block 2 is greater than the mass m_1 of block 1. The blocks are released from rest.

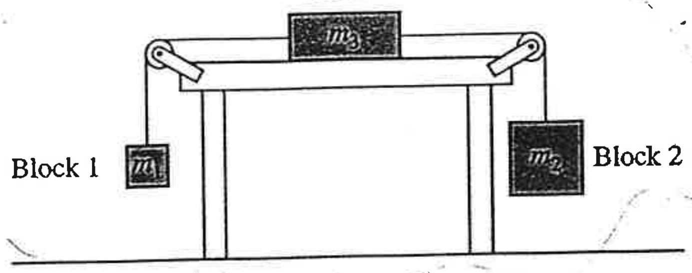
   (a) The dots below represent the two blocks. Draw free-body diagrams showing and labeling the forces (not components) exerted on each block. Draw the relative lengths of all vectors to reflect the relative magnitudes of all the forces.

   Block 1 Block 2



   (b) Derive the magnitude of the acceleration of block 2. Express your answer in terms of m_1, m_2, and g.

Block 3 of mass m_3 is added to the system, as shown below. There is no friction between block 3 and the table.



Note: Figure not drawn to scale.

(c) Indicate whether the magnitude of the acceleration of block 2 is now larger, smaller, or the same as in the original two-block system. Explain how you arrived at your answer.

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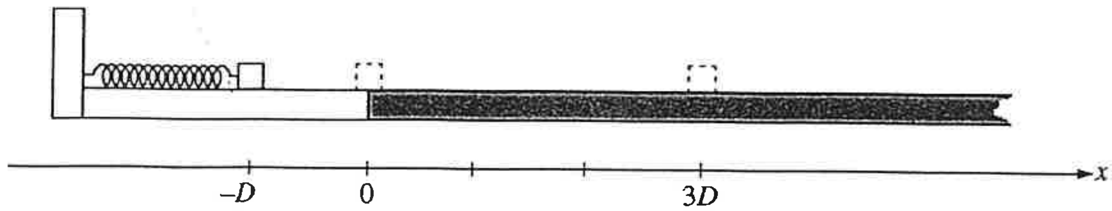


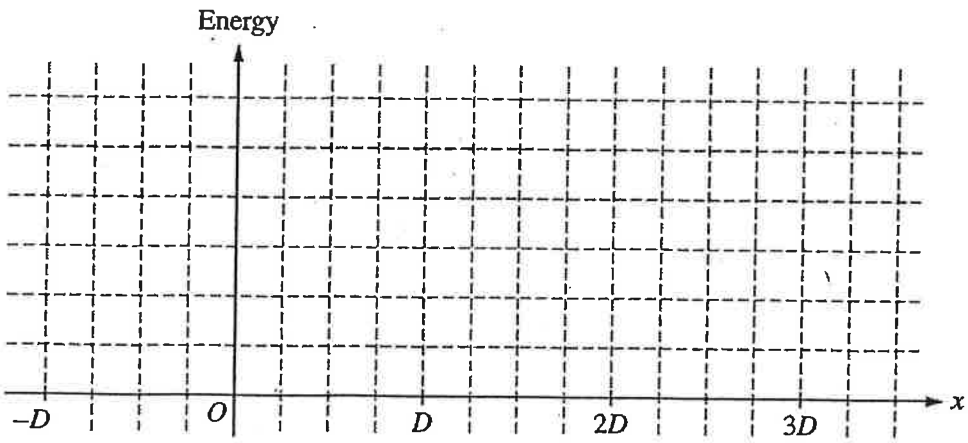
3. (12 points, suggested time 25 minutes)

A block is initially at position $x = 0$ and in contact with an uncompressed spring of negligible mass. The block is pushed back along a frictionless surface from position $x = 0$ to $x = -D$, as shown above, compressing the spring by an amount $\Delta x = D$. The block is then released. At $x = 0$ the block enters a rough part of the track and eventually comes to rest at position $x = 3D$. The coefficient of kinetic friction between the block and the rough track is μ.

(a) On the axes below, sketch and label graphs of the following two quantities as a function of the position of the block between $x = -D$ and $x = 3D$. You do not need to calculate values for the vertical axis, but the same vertical scale should be used for both quantities.

i. The kinetic energy K of the block

ii. The potential energy U of the block-spring system



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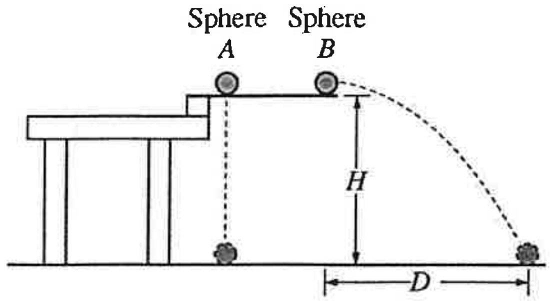
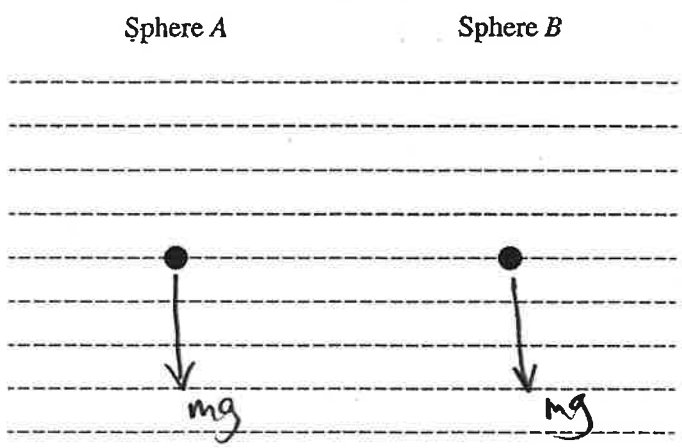


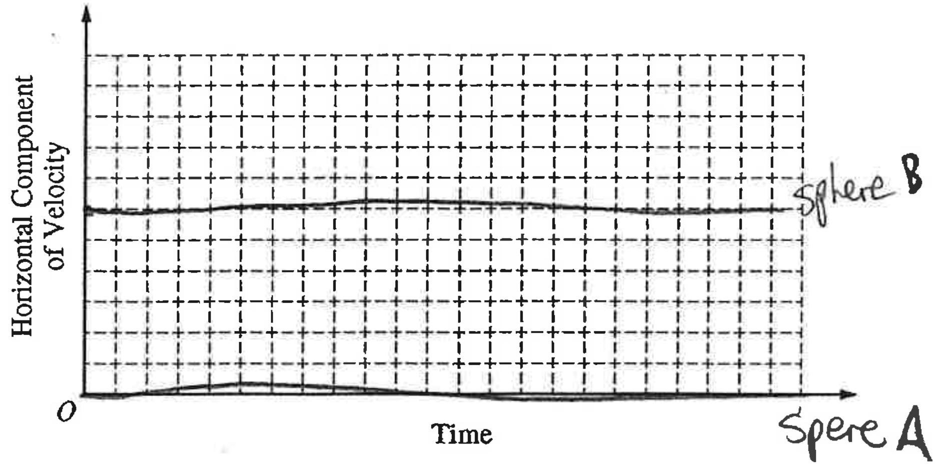
4. (7 points, suggested time 13 minutes)

Two identical spheres are released from a device at time $t = 0$ from the same height H, as shown above. Sphere A has no initial velocity and falls straight down. Sphere B is given an initial horizontal velocity of magnitude v_0 and travels a horizontal distance D before it reaches the ground. The spheres reach the ground at the same time t_f, even though sphere B has more distance to cover before landing. Air resistance is negligible.

(a) The dots below represent spheres A and B. Draw a free-body diagram showing and labeling the forces (not components) exerted on each sphere at time $\frac{t_f}{2}$.



(b) On the axes below, sketch and label a graph of the horizontal component of the velocity of sphere A and of sphere B as a function of time.



(c) In a clear, coherent, paragraph-length response, explain why the spheres reach the ground at the same time even though they travel different distances. Include references to your answers to parts (a) and (b).

The spring is now compressed twice as much, to $\Delta x = 2D$. A student is asked to predict whether the final position of the block will be twice as far at $x = 6D$. The student reasons that since the spring will be compressed twice as much as before, the block will have more energy when it leaves the spring, so it will slide farther along the track before stopping at position $x = 6D$.

(b)

i. Which aspects of the student's reasoning, if any, are correct? Explain how you arrived at your answer.

ii. Which aspects of the student's reasoning, if any, are incorrect? Explain how you arrived at your answer.

(c) Use quantitative reasoning, including equations as needed, to develop an expression for the new final position of the block. Express your answer in terms of D.

(d) Explain how any correct aspects of the student's reasoning identified in part (b) are expressed by your mathematical relationships in part (c). Explain how your relationships in part (c) correct any incorrect aspects of the student's reasoning identified in part (b). Refer to the relationships you wrote in part (c), not just the final answer you obtained by manipulating those relationships.

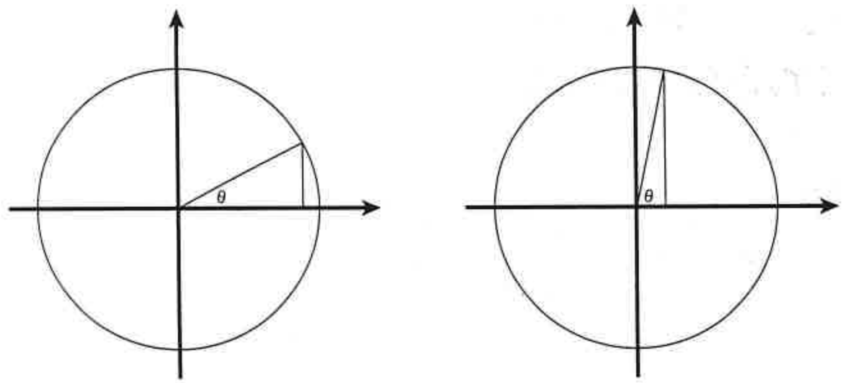


Figure 2.5: Changing Angles

In trigonometry, there are functions—known as **trigonometric functions**—that define the relationships between the angle and these sides (the opposite and the adjacent). These functions are given below.

Trigonometric Functions

$$\sin\theta = \frac{o}{h} \qquad \sec\theta = \frac{1}{\cos\theta} = \frac{h}{a}$$

$$\cos\theta = \frac{a}{h} \qquad \csc\theta = \frac{1}{\sin\theta} = \frac{h}{o}$$

$$\tan\theta = \frac{\sin\theta}{\cos\theta} = \frac{o}{a} \qquad \cot\theta = \frac{\cos\theta}{\sin\theta} = \frac{a}{o}$$

These functions are known as the **sine** (sin), the **cosine** (cos), the **tangent** (tan), the **secant** (sec), the **cosecant** (csc), and finally the **cotangent** (cot).

A mnemonic for these functions is SOHCAHTOA (pronounce it like "so-ca-toe-a").

SOHCAHTOA

$$\sin = \frac{\text{opposite}}{\text{hypotenuse}} \qquad \cos = \frac{\text{adjacent}}{\text{hypotenuse}} \qquad \tan = \frac{\text{opposite}}{\text{adjacent}}$$

You need only to remember how to construct the sine and cosine functions. After that, all of the other trigonometric functions are combinations of sine and cosine.

You should think about these trigonometric functions as ratios of these sides. The sine is a ratio of the opposite side and the hypotenuse. The cosine is a ratio of the adjacent side and the hypotenuse. These ratios can be easily found with a calculator, but there are a few ratios at specific angles that are important to remember. These are given in the table below:

Angle	$\sin\theta$	$\cos\theta$
0°	0	1
30°	0.5	$\frac{\sqrt{3}}{2}$
45°	$\frac{\sqrt{2}}{2}$	$\frac{\sqrt{2}}{2}$
60°	$\frac{\sqrt{3}}{2}$	0.5
90°	1	0

As mentioned before, when the angle is small, the adjacent edge is large and the opposite edge is small. So, at an angle of 0°, the opposite edge has a length of 0. Therefore, the sine function is also 0. Since there is no opposite edge, the hypotenuse is the same length as the adjacent edge at an angle of 0°. This is why the cosine function is 1 at this angle. The opposite is true for 90°.

When we discuss vectors in a few sections, trigonometry will be very important, so it is essential to understand the basics presented here. Applications will be discussed in the section on vectors.